

Frequency Inverters
WJ200 Series
Compact Inverter



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Compact Inverter

## Industry leading performance

#### ■ High starting torque of 200% or greater achieved using sensorless vector control

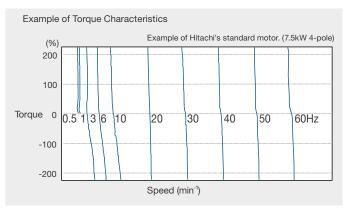
(when sized for heavy duty)

Sensorless vector control allows for the realisation of high torque required for applications such as cranes, hoist, lifts etc.

Auto-tuning function makes the implementation of sensorless vector control easy and effective.

#### Dual rating

WJ200 can be used for both heavy and normal duty. One-frame-size smaller WJ200 can be applicable to certain applications.



#### Trip avoidance functions

Minimum time deceleration function, over-current suppression and DC bus AVR functions are included as standard. These functions increase the robustness of the product and

Minimum time deceleration Function

OFF

ON

Motor Current

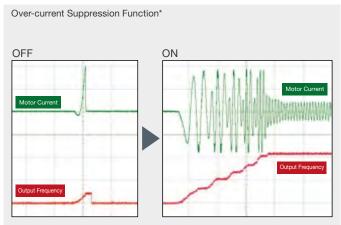
Output Frequency

Deceleration
Time: 4.2 sec.

Deceleration
Time: 1.9 sec.

2.3 sec. reduction of deceleration time without a braking resistor can be achieved when the function is active.

help to avoid unnecessary tripping. Improved torque limiting/current limiting function enables a load restriction to protect machinery and equipment. (Example of WJ200-075LF)



\*Turn off this function for lifting equipment.

#### Model Name Indication

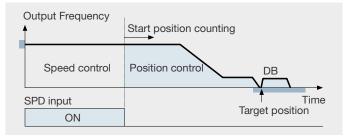


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## Simple positioning control

(in combination with a feedback signal)

When simple positioning function is activated, speed control operation or positioning control operation is selectable via intelligent input. While the [SPD] input is ON, the current position counter is held at 0. When [SPD] is OFF, the inverter enters positioning control operation and the position counter is active.



# Induction motor & Permanent magnet motor\* control with one inverter series

The WJ200 inverter can be used to drive both induction motors (IM) and permanent magnetic motors (PM).

PM motors are energy efficient and make effective use of available space.



<sup>\*</sup>The permanent magnet motor control function is only suitable for variable torque applications such as fan and pump.

### Model Line-up

Model Name WJ200-xxx	1-phase 2	00V class	3-phase 400V class		
	VT	CT	VT	CT	
002	0.4	0.2			
004	0.55	0.4	0.75	0.4	
007	1.1	0.75	1.5	0.75	
015	2.2	1.5	2.2	1.5	
022	3.0	2.2	3.0	2.2	
030			4.0	3.0	
040			5.5	4.0	
055			7.5	5.5	
075			11	7.5	
110			15	11	
150			18.5	15	

3-phase 200 V class versions are also available



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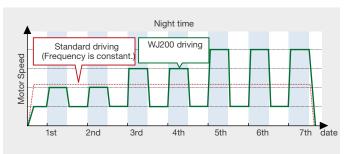
Compact Inverter

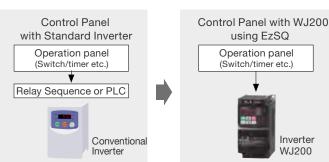
#### Ease of Use

#### Easy sequence programming function [EzSQ]

Logic operations can be realised within the inverter using Hitachi's EzSQ software without the need for external relavs or a PLC. User programs are compiled using a PC program which are then downloaded to the drive.

- EzSQ Application Example: Energy saving through speed reduction on a spinning machine.
- Daytime: Motor speed is automatically reduced to reduce demand during peak hours.
- Night-time: Motor speed is increased to take an advantage of offpeak power rates. Average productivity is maintained.

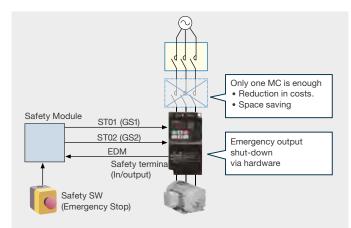




#### Safety stop function

WJ200 conforms to the applicable safety standards and corresponds to Machinery Directive of Europe. Inverter is shut down via hardware, bypassing the CPU, achieving a reliable safe stop function.

(ISO13849-1 Category 3 / IEC60204-1 Stop Category 0)



#### Password function

The WJ200 inverter has a password function to prevent changing parameters or to hide some or all parameters.

#### Ease of Maintenance

## Long life time for wearing parts

Design lifetime 10 Years or more\* for DC bus capacitors and The cooling fan can be exchanged without special tools. cooling fan.

Cooling fan ON/OFF control function for longer fan life.

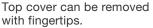
\*Ambient temperature: Average 40°C (no corrosive gases. oil mist or dust) Design lifetime is calculated, and not guaranteed.

## Life time warning function

WJ200 diagnoses lifetime of DC bus capacitors and cooling fan(s).

#### Easy to remove cooling fan







Remove cooling fan simply by disconnecting the power plug.

## **Environmental Friendliness**

#### EU RoHS compliant

Environment-friendly inverter meets RoHS requirements

#### Improvement of environment

Varnish coating of internal PC board is standard. (Logic PCB and I/F PCB are excluded.)

#### Micro surge voltage suppress function

Hitachi original PWM control method limits motor terminal voltage to less than twice inverter DC bus voltage. (During regeneration, the motor terminal voltage may exceed the motor maximum insulation voltage.)

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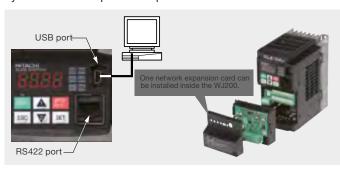




#### Network compatibility & External ports

USB (Mini-B connector) port and RS422 (RJ45 connector) port are available as standard.

Modbus/RTU serial communication is available as standard. The WJ200 can also be connected to various other fieldbus systems via an optional expansion card.



#### Ease of wiring

Screw-less terminals (control circuit terminals) spring-loaded, for use with solid or stranded wire with ferrules.

Screw-less terminals (Control circuit terminals)



#### Easy to configure

Various display modes for easy selection of displayed parameters

- Basic display
   Display most frequently used parameters.
- Data comparison function
   Display parameters changed from default setting.
- Quick display
   Display 32 user-selected parameters.
- Change history
   Store and display the most recent parameters changed by the user (Up to 32 items).
- Active parameter display
   Display those parameters which are enabled.

#### ■ Side-by-side installation

Inverters can be installed with no space between them to save space in the panel. \*Ambient temperature 40°C max., individual mounting.



#### Various Versatile Functions

#### Output monitoring (2 terminals)

Two programmable output terminals (Analog  $0 \sim 10VDC$  (10-bit), pulse train ( $0 \sim 10VDC$ , max 32kHz)) can be used to monitor items such as frequency, motor current etc.

#### Watt-hour monitor

Energy consumption is displayed in kWh.

#### Built-in BRD circuit

Built-in braking resistor control circuit as standard in all models (Resistor optional).

#### EzCOM (Peer-to-Peer communication)

WJ200 supports Peer-to-Peer communication between multiple inverters using the built-in RS485 port. One administrator inverter is necessary in the network, and the other inverters act as master or slave.

#### Flexible display functions

#### Automatic return to the initial display:

10 min. after the last key operation, display returns to the initial parameter set.

#### Display limitation:

Show only the contents of display parameter.

#### **Dual monitor:**

Two arbitrary monitor items can be set. Parameters are selected via the UP/DOWN keys.

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# Standard Specifications

#### ■ 1-phase 200V class

	Models WJ20	00		002SF	004SF	007SF	015SF	022SF		
A 1: 1- 1		VT	0.4	0.55	1.1	2.2	3.0			
Applicad	Applicable motor size kW		CT	0.2	0.4	0.75	1.5	2.2		
200V		2001/	VT	0.6	1.2	2.0	3.3	4.1		
		2000	CT	0.5	1.0	1.7	2.7	3.8		
nateu ca	Rated capacity (kVA)	240V	VT	0.7	1.4	2.4	3.9	4.9		
			CT	0.6	1.2	2.0	3.3	4.5		
lana a sak	Rated input voltage (V)			1-phase: 200V-15% to 240V +10%, 50/60Hz ±5%						
Input Rating	Rated input current (A)		VT	3.6	7.3	13.8	20.2	24.0		
Hatting			CT	3.0	6.3	11.5	16.8	22.0		
0	Rated output volt	age (V)		3-phase: 200 to 240V (proportional to input voltage)						
Output Rating	Rated output current (A)		VT	1.9	3.5	6.0	9.6	12.0		
			CT	1.6	3.0	5.0	8.0	11.0		
Minimum value of resistor (Ω)				100	100 100		50 50			
Weight kg			kg	1.0	1.1	1.6	1.8	1.8		

#### ■ 3-phase 400V class

a prided reev class													
Models WJ200			004HF	007HF	015HF	022HF	030HF	040HF	055HF	075HF	110HF	150HF	
Applicable motor size		Is\A/	VT	0.75	1.5	2.2	3.0	4.0	5.5	7.5	11	15	18.5
Applicab	able motor size kW		CT	0.4	0.75	1.5	2.2	3.0	4.0	5.5	7.5	11	15
		380V	VT	1.3	2.6	3.5	4.5	5.7	7.3	11.5	15.1	20.4	25.0
Datadaa			CT	1.1	2.2	3.1	3.6	4.7	6.0	9.7	11.8	15.7	20.4
Rated ca	pacity (kVA)	480V	VT	1.7	3.4	4.4	5.7	7.3	9.2	14.5	19.1	25.7	31.5
			CT	1.4	2.8	3.9	4.5	5.9	7.6	12.3	14.9	19.9	25.7
	Rated input voltage (V)			3-phase: 380V-15% to 480V +10%, 50/60Hz ±5%									
Input Rating	Bated input current (A)		VT	2.1	4.3	5.9	8.1	9.4	13.3	20.0	24.0	38.0	44.0
riating			CT	1.8	3.6	5.2	6.5	7.7	11.0	16.9	18.8	29.4	35.9
0	Rated output voltage (V)			3-phase: 380 to 480V (proportional to input voltage)									
Output Rating	Rated output current (A)		VT	2.1	4.1	5.4	6.9	8.8	11.1	17.5	23.0	31.0	38.0
			CT	1.8	3.4	4.8	5.5	7.2	9.2	14.8	18.0	24.0	31.0
Minimum	Minimum value of resistor (Ω)			180	180	180	100	100	100	70	70	70	35
Weight kg			1.5	1.6	1.8	1.9	1.9	2.1	3.5	3.5	4.7	5.2	

VT normal duty / CT heavy duty

## Global standards

#### Conformity to global standards

CE, UL, c-UL, c-Tick approvals.



#### Sink / source logic is standard

Logic input and output terminals can be configured for sink or source logic.

#### ■ Wide input power voltage range

Input voltage 240V for 200V class and 480V for 400V class as standard.

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<sup>3-</sup>phase 200 V class versions are also available

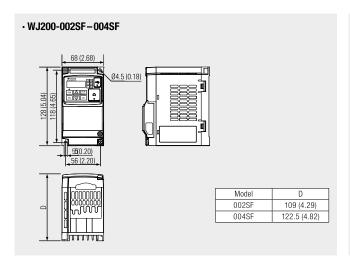


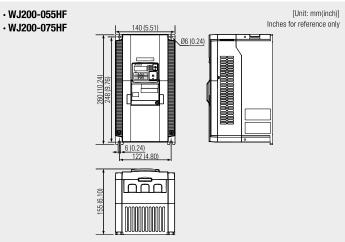


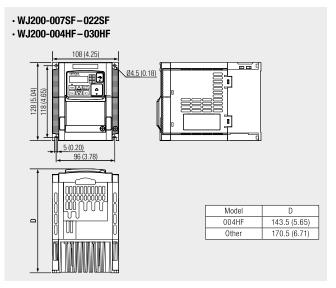
# **General Specifications**

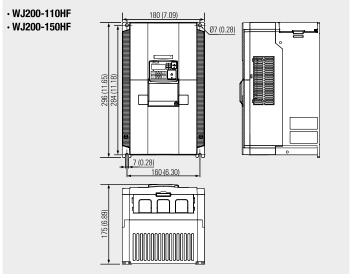
general output (EzSQ)  Pulse train output  Functions    Functions   Terminals   1 terminal, 0-10VDC, 32kHz max.	Item		า	General Specifications						
Carrier frequency   Self-tip 1 SkHz (derating required depending on the model)	Pro	Protective housing		IP20						
Digital command: ±0.01% of the maximum frequency   Digital command: ±0.02% of the maximum frequency   Caregory   Analog command: ±0.02% of the maximum frequency   Caregory	Cor	Control method		Sinusoidal Pulse Width Modulation (PWM) control						
Prequency accuracy	Car	Carrier frequency		2kHz to 15kHz (derating required depending on the model)						
Frequency accuracy  Anslag command: ±0.2% of the maximum frequency (25°C±10°C)  Digital: 0.0114; Analog max. Frequency (750°C±10°C)  Digital: 0.0114; Analog max. Frequency (750°C±10°C)  Volt / Freq. characteristic  VF control (constant forque, reduced torque, free-V/F): base freq. 30Hz-400Hz adjustable, Sensorless vector control, Ologoel dop control with motor encoder feedback (only V/F control).  Darating: CT (Heavy duty): 60 sec. 6150%  VF (Normal duty): 60 sec. 6150%  Acceleration / deceleration time  Do the first of	Out	Output frequency range		0.1 to 400Hz						
Volt./Freq. characteristic   Vir Control (constant torque, reduced torque, free-VF): base freq. 30Hz: 40DHz adjustable. Sensorless vector control. (losed dop control with motor encoder feedback (only VF control).	Fre	Frequency accuracy		, ,						
Sensoriess vector control, Closed loop control with motor encoder feedback (only V/F control).	Fre	quency setting re	solution							
Overload capacity  V T Normal duty): 60 sec. 9120%  Acceleration (Acceleration time   Starting torque   Do braking    Operator panel   External signal   Doperator panel   External signal   External signal   Doperator panel   Dop	Vol	t./Freq. characte	ristic							
Starting lorque	Ove	erload capacity								
Operator panel   A	Acc	celeration/decele	ration time	0.01 to 3600 seconds, linear and S-curve accel/decel, second accel/decel setting available						
Preq. setting	Sta	rting torque		200% @0.5Hz (sensorless vector control)						
Freq. setting	DC	braking								
FWD / REV run   Departor panel   External signal   Forward / Invalid   Fwo /			Operator panel	∆♥ keys/Value settings						
Deparator panel   External signal   Forward vn/Stop (Forward/Reverse run change by command)	Fre	q. setting	External signal	· · ·						
External signal   Forward run/Stop, Reverse run/stop   Via network   RS485 ModBus RTU, other network option   RS485 ModBus RTU, other network option   RS485 ModBus RTU, other network option   Pulse train input   Terminals   Terminals   Functions   68 functions assignable to each terminal (for the details, refer to the instruction manual)   Pulse train input   Terminals   2 terminal, 2/32kHz max. (one terminal is common with intelligent terminal [7])   Terminals   Terminals   2 open-collector terminal, No/NC swichable, sink logic   Terminals   Functions   48 functions assignable to each terminal			Via network	RS485 ModBus RTU, other network option						
External signal   Forward run/Stop, Reverse run/stop   Via network   RS485 ModBus RTU, other network option   RS485 ModBus RTU, other network option   RS485 ModBus RTU, other network option   Pulse train input   Terminals   Terminals   Functions   68 functions assignable to each terminal (for the details, refer to the instruction manual)   Pulse train input   Terminals   2 terminal, 2/32kHz max. (one terminal is common with intelligent terminal [7])   Terminals   Terminals   2 open-collector terminal, No/NC swichable, sink logic   Terminals   Functions   48 functions assignable to each terminal			Operator panel							
Via network   RS485 ModBus RTU, other network option   Terminals	FW	D/REV run								
Intelligent input   Functions   Functions   Functions   Get functions assignable to each terminal (for the details, refer to the instruction manual)				Transfer of the second						
Pulse train input   2 terminal, 2/32kHz max. (one terminal is common with intelligent terminal [7])	<u></u>	Intelligent input		· · ·						
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Intelligent output   Terminals   2 open-collector terminal, NO/NC swichable, sink logic   Terminal   Terminal   48 functions assignable to each terminal	ıt s		T dilotions							
Intelligent output   Terminals   2 open-collector terminal, NO/NC swichable, sink logic   Terminal   Terminal   48 functions assignable to each terminal	nbr	· ·								
terminal Functions 48 functions assignable to each terminal Monitor output (analog)  Functions   Terminal   1 terminal, 0 to 10VDC			Torminala							
Monitor output										
Functions   Functions   Pulse train output   Functions   Terminals   1 terminal, 0-10VDC, 32kHz max.   Pulse train output   Functions   Pulse train output   Functions   Pulse train output   Output frequency, output current, output torque, output voltage, input power, thermal load ratio, LAD freq., heat sink temperature general output (EzSQ)   Pulse train output   Output frequency, output current, pulse train input monitor   Output frequency, output current, pulse train input monitor   Prese-VF, manual / automatic torque boost, output voltage gain adjustment, AVR function, reduced voltage start, motor data selection, auto-tuning, motor stabilization control, reverse running protection, simple position control, simple torque control, torque limiting, automatic carrier frequency reduction, energy saving operation, PID function, non-stop operation at instantaneous power faillure, brake control, DC injection braking, dynamic braking (BRD), frequency upper and lower limiters, jump frequencies, curve accel and decel (S, U, inversed U,EL-S), 16-stage speed profile, fine adjustment of start frequency, accel and decel stop, process jogging, frequency calculation, frequency addition, 2-stage accel / decel, stop mode selection, saint / end freq., analog input filter, window comparations, input terminal response time, output signal delay / hold function, instant / end freq., analog input filter, window comparation, input terminal response time, output signal delay / hold function, display restriction, password function, user parameter, initialization, initial display selection, cooling fan control, warning, trip retry, frequency pull-in restart, frequency matching, overload parks resistor overload, CPU error, memory error, external trip, USP error, ground fault detection at power on, temperature error, internal communication error, driver error, thermistor error, brake error, safe stop, overload at	_			· ·						
Pulse train output  Punctions  Functions  ON for inverter alarm (1c contacts, both normally open or closed available.)  ON for inverter alarm (1c contacts, both normally open or closed available.)  Free-VF, manual / automatic torque boost, output voltage gain adjustment, AVR function, reduced voltage start, motor data selection, auto-tuning, motor stabilization control, reverse running protection, simple position control, simple torque control, torque limitiers, jump frequency reduction, energy saving operation, PID function, non-stop operation at instantaneous power failure, brake control, DC injection braking, dynamic braking (BRD), frequency upper and lower limiters, jump frequencies, curve accel and decel (S, U, inversed U,EL-S), 16-stage speed profile, fine adjustment of start frequency, accel and feed, analog input filter, window comparators, input terminal response time, output signal delay / hold function, rotation direction restriction, stop key selection, software lock, safe stop function, scaling function, display restriction, password function, user parameter, initialization, initial display selection, cooling fan control, warning, trip retry, frequency pull-in restart, frequency matching, overload restriction, over current restriction, DC bus voltage AVR  Over-current, over-voltage, under-voltage, overload, brake resistor overload, CPU error, memory error, external trip, USP error, ground fault detection at power on, temperature error, internal communication error, choose reror, safe stop, overload at low speed, modbus communication error, option error, encoder disconnection, speed excessive, EzSQ command error, EzSQ nesting error, EzSQ execution error, EzSQ user trip  Operating  Protective function  Temperature  Operating (ambient): -10 to 50°C / Storage: -20 to 65°C  Operating (ambient): -10 to 50°C / Storage: -20 to 65°C	signa			Output freq., output current, output torque, output voltage, input power, thermal load ratio, LAD freq., heat sink temperature,						
Pulse train output  Punctions  Functions  ON for inverter alarm (1c contacts, both normally open or closed available.)  ON for inverter alarm (1c contacts, both normally open or closed available.)  Free-VF, manual / automatic torque boost, output voltage gain adjustment, AVR function, reduced voltage start, motor data selection, auto-tuning, motor stabilization control, reverse running protection, simple position control, simple torque control, torque limitiers, jump frequency reduction, energy saving operation, PID function, non-stop operation at instantaneous power failure, brake control, DC injection braking, dynamic braking (BRD), frequency upper and lower limiters, jump frequencies, curve accel and decel (S, U, inversed U,EL-S), 16-stage speed profile, fine adjustment of start frequency, accel and feed, analog input filter, window comparators, input terminal response time, output signal delay / hold function, rotation direction restriction, stop key selection, software lock, safe stop function, scaling function, display restriction, password function, user parameter, initialization, initial display selection, cooling fan control, warning, trip retry, frequency pull-in restart, frequency matching, overload restriction, over current restriction, DC bus voltage AVR  Over-current, over-voltage, under-voltage, overload, brake resistor overload, CPU error, memory error, external trip, USP error, ground fault detection at power on, temperature error, internal communication error, choose reror, safe stop, overload at low speed, modbus communication error, option error, encoder disconnection, speed excessive, EzSQ command error, EzSQ nesting error, EzSQ execution error, EzSQ user trip  Operating  Protective function  Temperature  Operating (ambient): -10 to 50°C / Storage: -20 to 65°C  Operating (ambient): -10 to 50°C / Storage: -20 to 65°C	but									
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Free-V/F, manual / automatic torque boost, output voltage gain adjustment, AVR function, reduced voltage start, motor data selection, auto-tuning, motor stabilization control, reverse running protection, simple position control, simple torque control, torque limiting, automatic carrier frequency reduction, energy saving operation, PID function, non-stop operation at instantaneous power failure, brake control, DC injection braking, dynamic braking (BRD), frequency upper and lower limiters, jump frequencies, curve accel and decel (S, U, inversed U.EL-S), 16-stage speed profile, fine adjustment of start frequency, accel and decel stop, process jogging, frequency calculation, frequency addition, 2-stage accel / decel, stop mode selection, start / end freq., analog input filter, window comparators, input terminal response time, output signal delay / hold function, rotation direction restriction, stop key selection, software lock, safe stop function, scaling function, display restriction, password function, user parameter, initialization, initial display selection, cooling fan control, warning, trip retry, frequency pull-in restart, frequency matching, overload restriction, over current restriction, DC bus voltage AVR  Over-current, over-voltage, under-voltage, overload, brake resistor overload, CPU error, memory error, external trip, USP error, ground fault detection at power on, temperature error, internal communication error, driver error, thermistor error, brake error, safe stop, overload at low speed, modbus communication error, option error, encoder disconnection, speed excessive, EzSQ command error, EzSQ nesting error, EzSQ execution error, EzSQ user trip  Operating environment  Temperature  Operating (ambient): -10 to 50°C / Storage: -20 to 65°C  Humidity  20 to 90% humidity (non-condensing)  Vibration  5.9m/s² (0.6G), 10 to 55 Hz  Location  Altitude 1,000m or less, indoors (no corrosive gasses or dust)			Functions	Output freq., output current, output torque, output voltage, input power, thermal load ratio, LAD freq., heat sink temperature, general output (EzSQ) [Pulse train output]						
Free-V/F, manual / automatic torque boost, output voltage gain adjustment, AVR function, reduced voltage start, motor data selection, auto-tuning, motor stabilization control, reverse running protection, simple position control, simple torque control, torque limiting, automatic carrier frequency reduction, energy saving operation, PID function, non-stop operation at instantaneous power failure, brake control, DC injection braking, dynamic braking (BRD), frequency upper and lower limiters, jump frequencies, curve accel and decel (S, U, inversed U.EL-S), 16-stage speed profile, fine adjustment of start frequency, accel and decel stop, process jogging, frequency calculation, frequency addition, 2-stage accel / decel, stop mode selection, start / end freq., analog input filter, window comparators, input terminal response time, output signal delay / hold function, rotation direction restriction, stop key selection, software lock, safe stop function, scaling function, display restriction, password function, user parameter, initialization, initial display selection, cooling fan control, warning, trip retry, frequency pull-in restart, frequency matching, overload restriction, over current restriction, DC bus voltage AVR  Over-current, over-voltage, under-voltage, overload, brake resistor overload, CPU error, memory error, external trip, USP error, ground fault detection at power on, temperature error, internal communication error, driver error, thermistor error, brake error, safe stop, overload at low speed, modbus communication error, option error, encoder disconnection, speed excessive, EzSQ command error, EzSQ nesting error, EzSQ execution error, EzSQ user trip  Operating environment  Temperature  Operating (ambient): -10 to 50°C / Storage: -20 to 65°C  Humidity  20 to 90% humidity (non-condensing)  Vibration  5.9m/s² (0.6G), 10 to 55 Hz  Location  Altitude 1,000m or less, indoors (no corrosive gasses or dust)		Alarm output co	ntact (relay)	ON for inverter alarm (1c contacts, both normally open or closed available.)						
Protective function error, ground fault detection at power on, temperature error, internal communication error, driver error, thermistor error, brake error, safe stop, overload at low speed, modbus communication error, option error, encoder disconnection, speed excessive, EzSQ command error, EzSQ execution error, EzSQ user trip  Temperature Operating (ambient): -10 to 50°C / Storage: -20 to 65°C  Humidity 20 to 90% humidity (non-condensing)  Vibration 5.9m/s² (0.6G), 10 to 55 Hz  Location Altitude 1,000m or less, indoors (no corrosive gasses or dust)  Coating color Black				Free-V/F, manual / automatic torque boost, output voltage gain adjustment, AVR function, reduced voltage start, motor data selection, auto-tuning, motor stabilization control, reverse running protection, simple position control, simple torque control, torque limiting, automatic carrier frequency reduction, energy saving operation, PID function, non-stop operation at instantaneous power failure, brake control, DC injection braking, dynamic braking (BRD), frequency upper and lower limiters, jump frequencies, curve accel and decel (S, U, inversed U,EL-S), 16-stage speed profile, fine adjustment of start frequency, accel and decel stop, process jogging, frequency calculation, frequency addition, 2-stage accel / decel, stop mode section, start / end freq., analog input filter, window comparators, input terminal response time, output signal delay / hold function, rotation direction restriction, stop key selection, software lock, safe stop function, scaling function, display restriction, password function, user parameter, initialization, initial display selection, cooling fan control, warning, trip retry, frequency						
Operating environment    Humidity   20 to 90% humidity (non-condensing)	Pro	tective function		error, ground fault detection at power on, temperature error, internal communication error, driver error, thermistor error, brake error, safe stop, overload at low speed, modbus communication error, option error, encoder disconnection, speed excessive, EzSQ command error, EzSQ nesting error, EzSQ execution error, EzSQ user trip						
environment  Vibration 5.9m/s² (0.6G), 10 to 55 Hz  Location Altitude 1,000m or less, indoors (no corrosive gasses or dust)  Coating color Black										
Location Altitude 1,000m or less, indoors (no corrosive gasses or dust)  Coating color Black			Humidity	20 to 90% humidity (non-condensing)						
Coating color Black	env	ironment	Vibration	5.9m/s <sup>2</sup> (0.6G), 10 to 55 Hz						
			Location	Altitude 1,000m or less, indoors (no corrosive gasses or dust)						
Options Remote operator unit, cables for the units, braking unit, braking resistor, AC reactor, DC reactor, EMC filter	Coa	ating color		Black						
	Opt	tions		Remote operator unit, cables for the units, braking unit, braking resistor, AC reactor, DC reactor, EMC filter						

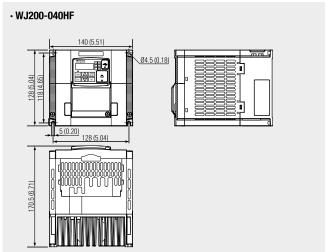
# **Dimensions**











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